Structural Equation Models: The General Case¹ STA431 Spring 2023

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Features of Structural Equation Models

- Multiple equations.
- All the variables are random.
- An explanatory variable in one equation can be the response variable in another equation.
- Models are represented by path diagrams.
- Identifiability is always an issue.
- The statistical models are models of influence. They are *causal models*.

Modest changes in notation

$$Y_{i,1} = \alpha_1 + \gamma_1 X_{i,1} + \gamma_2 X_{i,2} + \epsilon_{i,1}$$

$$Y_{i,2} = \alpha_2 + \beta Y_{i,1} + \epsilon_{i,2}$$

- Regression coefficients (links between exogenous variables and endogenous variables) are now called gamma instead of beta.
- Betas are used for links between endogenous variables.
- Intercepts will soon disappear.

Example: A Path Model with Measurement Error



$$Y_{i,1} = \alpha_1 + \gamma_1 X_i + \epsilon_{i,1}$$

$$Y_{i,2} = \alpha_2 + \beta Y_{i,1} + \gamma_2 X_i + \epsilon_{i,2}$$

$$W_i = \nu_1 + \lambda_1 X_i + e_{i,1}$$

$$V_{i,1} = \nu_2 + \lambda_2 Y_{i,1} + e_{i,2}$$

$$V_{i,2} = \nu_3 + \lambda_3 Y_{i,2} + e_{i,3}$$

The General (original) Model: Independently for i = 1, ..., n, let

$$egin{array}{rcl} \mathbf{y}_i &=& oldsymbol{lpha} + oldsymbol{eta} \mathbf{y}_i + oldsymbol{\Gamma} \mathbf{x}_i + oldsymbol{\epsilon}_i \ \mathbf{F}_i &=& egin{pmatrix} \mathbf{x}_i \ \mathbf{y}_i \ \mathbf{y}_i \ \end{pmatrix} \ \mathbf{d}_i &=& oldsymbol{
u} + oldsymbol{\Lambda} \mathbf{F}_i + \mathbf{e}_i, ext{ where} \end{array}$$

- \mathbf{y}_i is a $q \times 1$ latent random vector.
- α is a $q \times 1$ vector of constants.
- β is a $q \times q$ matrix of constants with zeros on the main diagonal.
- Γ is a $q \times p$ matrix of constants.
- \mathbf{x}_i is a $p \times 1$ latent random vector with expected value $\boldsymbol{\mu}_x$ and positive definite covariance matrix $\boldsymbol{\Phi}_x$.
- ϵ_i is a $q \times 1$ latent random vector with expected value zero and positive definite covariance matrix Ψ .
- \mathbf{F}_i (*F* for Factor) is a partitioned vector with \mathbf{x}_i stacked on top of \mathbf{y}_i . It is a $(p+q) \times 1$ latent random vector whose expected value is denoted by $\boldsymbol{\mu}_F$, and whose variance-covariance matrix is denoted by $\boldsymbol{\Phi}$.
- d_i is a k × 1 observable random vector. The expected value of d_i will be denoted by μ, and the covariance matrix of d_i will be denoted by Σ.
- $\boldsymbol{\nu}$ is a $k \times 1$ vector of constants.
- Λ is a $k \times (p+q)$ matrix of constants.
- e_i is a k × 1 latent random vector with expected value zero and covariance matrix Ω, which need not be positive definite.
- $\mathbf{x}_i, \, \boldsymbol{\epsilon}_i$ and \mathbf{e}_i are independent.

$\begin{array}{l} Surrogate \ Models \\ Truth \approx Original \ Model \rightarrow Surrogate \ Model \ 1 \rightarrow Surrogate \ Model \ 2 \ \dots \end{array}$

- We more or less accept the original model, but we can't identify the parameters.
- So we re-parameterize, obtaining a surrogate model. Repeat.
- We will carefully keep track of the *meaning* of the new parameters in terms of the parameters of the original model.

$$egin{array}{rcl} \mathbf{y}_i &=& oldsymbol{lpha} + oldsymbol{eta} \mathbf{y}_i + oldsymbol{\Gamma} \mathbf{x}_i + oldsymbol{\epsilon}_i \ \mathbf{F}_i &=& igg(rac{\mathbf{x}_i}{\mathbf{y}_i}igg) \ \mathbf{d}_i &=& oldsymbol{
u} + oldsymbol{\Lambda} \mathbf{F}_i + \mathbf{e}_i \end{array}$$

where ...

- Carefully count the parameters that appear only in $E(\mathbf{d}_i) = \boldsymbol{\mu}$ and not in $cov(\mathbf{d}_i)$.
- There are more of these parameters than elements of $E(\mathbf{d}_i)$.
- Parameter count rule.

Center the model

- There are too many expected values and intercepts to identify.
- Center all the random variables in the model by adding and subtracting expected values.
- Obtain a *centered surrogate model*

$$egin{array}{rcl} \overset{c}{\mathbf{y}}_{i} &=& eta \overset{c}{\mathbf{y}}_{i} + \mathbf{\Gamma} \overset{c}{\mathbf{x}}_{i} + m{\epsilon}_{i} \ \overset{c}{\mathbf{F}}_{i} &=& \left(rac{\overset{c}{\mathbf{x}}_{i}}{\overset{c}{\mathbf{y}}_{i}}
ight) \ \overset{c}{\mathbf{d}}_{i} &=& \mathbf{\Lambda} \overset{c}{\mathbf{F}}_{i} + \mathbf{e}_{i} \end{array}$$

• Same β , Γ and Λ , same variances and covariances.

- Centering is a change of variables.
- Expected values and intercepts are gone, and the dimension of the parameter space is reduced.
- Drop the little *c* over the random vectors.

The General Centered Model

Independently for $i = 1, \ldots, n$,

$$egin{array}{rcl} \mathbf{y}_i &=& eta \mathbf{y}_i + \mathbf{\Gamma} \mathbf{x}_i + eta_i \ \mathbf{F}_i &=& \left(rac{\mathbf{x}_i}{\mathbf{y}_i}
ight) \ \mathbf{d}_i &=& \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i \end{array}$$

- \mathbf{d}_i (the data) are observable. All other variables are latent.
- $\mathbf{y}_i = \beta \mathbf{y}_i + \mathbf{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i$ is called the *Latent Variable Model*.
- The latent vectors \mathbf{x}_i and \mathbf{y}_i are collected into a *factor* \mathbf{F}_i .
- $\mathbf{d}_i = \mathbf{A}\mathbf{F}_i + \mathbf{e}_i$ is called the *Measurement Model*.

$\mathbf{y}_i = oldsymbol{eta} \mathbf{y}_i + oldsymbol{\Gamma} \mathbf{x}_i + oldsymbol{\epsilon}_i \qquad \mathbf{F}_i = \left(rac{\mathbf{x}_i}{\mathbf{y}_i} ight) \quad \mathbf{d}_i = oldsymbol{\Lambda} \mathbf{F}_i + \mathbf{e}_i$

- \mathbf{y}_i is a $q \times 1$ latent random vector.
- β is a $q \times q$ matrix of constants with zeros on the main diagonal.
- \mathbf{x}_i is a $p \times 1$ latent random vector.
- Γ is a $q \times p$ matrix of constants.
- ϵ_i is a $q \times 1$ vector of error terms.
- \mathbf{F}_i (*F* for Factor) is just \mathbf{x}_i stacked on top of \mathbf{y}_i . It is a $(p+q) \times 1$ latent random vector.
- \mathbf{d}_i is a $k \times 1$ observable random vector. Sometimes, $\mathbf{d}_i = \left(\frac{\mathbf{w}_i}{\mathbf{v}_i}\right)$.
- Λ is a $k \times (p+q)$ matrix of constants: "factor loadings."
- \mathbf{e}_i is a $k \times 1$ vector of error terms.
- $\mathbf{x}_i, \, \boldsymbol{\epsilon}_i$ and \mathbf{e}_i are independent.

Parameters More notation

$$egin{array}{rcl} \mathbf{y}_i &=& eta \mathbf{y}_i + \mathbf{\Gamma} \mathbf{x}_i + eta_i \ \mathbf{F}_i &=& \left(egin{array}{c} \mathbf{x}_i \ \mathbf{y}_i \end{array}
ight) \ \mathbf{d}_i &=& \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i \end{array}$$

- Collect the unique elements of β , Γ , Λ , Φ_x , Ψ and Ω into a parameter vector θ .
- $\boldsymbol{\theta}$ is a *function* of the original model parameters.

Matrix Form



$$\begin{array}{rcl} \mathbf{y}_{i} & = & \boldsymbol{\beta} & \mathbf{y}_{i} & + & \boldsymbol{\Gamma} & \mathbf{x}_{i} & + & \boldsymbol{\epsilon}_{i} \\ \left(\begin{array}{c} Y_{i,1} \\ Y_{i,2} \end{array}\right) & = & \left(\begin{array}{c} 0 & 0 \\ \boldsymbol{\beta} & 0 \end{array}\right) & \left(\begin{array}{c} Y_{i,1} \\ Y_{i,2} \end{array}\right) & + & \left(\begin{array}{c} \gamma_{1} \\ \gamma_{2} \end{array}\right) & X_{i} & + & \left(\begin{array}{c} \epsilon_{i,1} \\ \epsilon_{i,2} \end{array}\right) \\ \mathbf{d}_{i} & = & \boldsymbol{\Lambda} & \mathbf{F}_{i} & + & \mathbf{e}_{i} \\ \left(\begin{array}{c} W_{i} \\ V_{i,1} \\ V_{i,2} \end{array}\right) & = & \left(\begin{array}{c} \lambda_{1} & 0 & 0 \\ 0 & \lambda_{2} & 0 \\ 0 & 0 & \lambda_{3} \end{array}\right) & \left(\begin{array}{c} X_{i} \\ Y_{i,1} \\ Y_{i,2} \end{array}\right) & + & \left(\begin{array}{c} e_{i,1} \\ e_{i,2} \\ e_{i,3} \end{array}\right) \end{array} \right) \end{array}$$

Observable variables in the "latent" variable model $\mathbf{y}_i = \boldsymbol{\beta} \mathbf{y}_i + \boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i$

Fairly common

- These present no problem.
- Let $P(e_j = 0) = 1$, so $Var(e_j) = 0$.
- And $Cov(e_i, e_j) = 0$
- Because if $P(e_j = 0) = 1$,

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$$Cov(e_i, e_j) = E(e_i e_j) - E(e_i)E(e_j)$$
$$= E(e_i \cdot 0) - E(e_i) \cdot 0$$
$$= 0 - 0 = 0$$

In Ω = cov(e_i), column j (and row j) are all zeros.
Ω singular, no problem.

What should you be able to do?

- Given a path diagram, write the model equations and say which exogenous variables are correlated with each other.
- Given the model equations and information about which exogenous variables are correlated with each other, draw the path diagram.
- Given either piece of information, write the model in matrix form and say what all the matrices are.
- Calculate model covariance matrices.
- Check identifiability.

Recall the notation

$$egin{array}{rcl} \mathbf{y}_i &=& eta \mathbf{y}_i + \mathbf{\Gamma} \mathbf{x}_i + eta_i \ \mathbf{F}_i &=& \left(rac{\mathbf{x}_i}{\mathbf{y}_i}
ight) \ \mathbf{d}_i &=& \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i \end{array}$$

Calculate a general expression for $\Sigma(\theta)$.

For the latent variable model, calculate $\mathbf{\Phi} = cov(\mathbf{F}_i)$ Have $cov(\mathbf{x}_i) = \mathbf{\Phi}_x$, need $cov(\mathbf{y}_i)$ and $cov(\mathbf{x}_i, \mathbf{y}_i)$

$$\begin{aligned} \mathbf{y}_i &= \boldsymbol{\beta} \mathbf{y}_i + \boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i \\ \Rightarrow & \mathbf{y}_i - \boldsymbol{\beta} \mathbf{y}_i = \boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i \\ \Rightarrow & \mathbf{I} \mathbf{y}_i - \boldsymbol{\beta} \mathbf{y}_i = \boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i \\ \Rightarrow & (\mathbf{I} - \boldsymbol{\beta}) \mathbf{y}_i = \boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i \\ \Rightarrow & (\mathbf{I} - \boldsymbol{\beta})^{-1} (\mathbf{I} - \boldsymbol{\beta}) \mathbf{y}_i = (\mathbf{I} - \boldsymbol{\beta})^{-1} (\boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i) \\ \Rightarrow & \mathbf{y}_i = (\mathbf{I} - \boldsymbol{\beta})^{-1} (\boldsymbol{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i) \end{aligned}$$

So,

$$cov(\mathbf{y}_i) = (\mathbf{I} - \boldsymbol{\beta})^{-1} cov(\mathbf{\Gamma}\mathbf{x}_i + \boldsymbol{\epsilon}_i)(\mathbf{I} - \boldsymbol{\beta})^{-1\top}$$

= $(\mathbf{I} - \boldsymbol{\beta})^{-1} (cov(\mathbf{\Gamma}\mathbf{x}_i) + cov(\boldsymbol{\epsilon}_i)) (\mathbf{I} - \boldsymbol{\beta}^{\top})^{-1}$
= $(\mathbf{I} - \boldsymbol{\beta})^{-1} (\mathbf{\Gamma}\boldsymbol{\Phi}_x \mathbf{\Gamma}^{\top} + \boldsymbol{\Psi}) (\mathbf{I} - \boldsymbol{\beta}^{\top})^{-1}$

Theorem: If the original model holds, $(\mathbf{I} - \boldsymbol{\beta})^{-1}$ exists.

 $\mathbf{y}_i = \boldsymbol{\alpha} + \boldsymbol{\beta} \mathbf{y}_i + \mathbf{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i$ yields $(\mathbf{I} - \boldsymbol{\beta}) \mathbf{y}_i = \boldsymbol{\alpha} + \mathbf{\Gamma} \mathbf{x}_i + \boldsymbol{\epsilon}_i$. Suppose $(\mathbf{I} - \boldsymbol{\beta})^{-1}$ does not exist.

Then the rows of $\mathbf{I} - \boldsymbol{\beta}$ are linearly dependent, and there is a $q \times 1$ non-zero vector of constants \mathbf{a} with $\mathbf{a}^{\top}(\mathbf{I} - \boldsymbol{\beta}) = 0$. So,

$$\mathbf{a}^{\top}(\mathbf{I} - \boldsymbol{\beta})\mathbf{y}_{i} = 0 = \mathbf{a}^{\top}\boldsymbol{\alpha} + \mathbf{a}^{\top}\boldsymbol{\Gamma}\mathbf{x}_{i} + \mathbf{a}^{\top}\boldsymbol{\epsilon}_{i}$$

$$\Rightarrow Var(0) = Var(\mathbf{a}^{\top}\boldsymbol{\Gamma}\mathbf{x}_{i}) + Var(\mathbf{a}^{\top}\boldsymbol{\epsilon}_{i})$$

$$\Rightarrow 0 = \mathbf{a}^{\top}\boldsymbol{\Gamma}\boldsymbol{\Phi}_{x}\boldsymbol{\Gamma}^{\top}\mathbf{a} + \mathbf{a}^{\top}\boldsymbol{\Psi}\mathbf{a} > 0.$$

Contradicts $\mathbf{I} - \boldsymbol{\beta}$ singular.

$|\mathbf{I} - \boldsymbol{\beta}| \neq 0$ can create a hole in the parameter space.

- Have $cov(\mathbf{y}_i) = (\mathbf{I} \boldsymbol{\beta})^{-1} \left(\boldsymbol{\Gamma} \boldsymbol{\Phi}_x \boldsymbol{\Gamma}^\top + \boldsymbol{\Psi} \right) (\mathbf{I} \boldsymbol{\beta}^\top)^{-1}.$
- Know $cov(\mathbf{x}_i) = \mathbf{\Phi}_x$
- Easy to get $cov(\mathbf{x}_i, \mathbf{y}_i)$.

For the measurement model, calculate $\Sigma = cov(\mathbf{d}_i)$

$$\begin{aligned} \mathbf{d}_i &= \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i \\ \Rightarrow cov(\mathbf{d}_i) &= cov(\mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i) \\ &= cov(\mathbf{\Lambda} \mathbf{F}_i) + cov(\mathbf{e}_i) \\ &= \mathbf{\Lambda} cov(\mathbf{F}_i) \mathbf{\Lambda}^\top + cov(\mathbf{e}_i) \\ &= \mathbf{\Lambda} \mathbf{\Phi} \mathbf{\Lambda}^\top + \mathbf{\Omega} \\ &= \mathbf{\Sigma} \end{aligned}$$

Two-stage Proofs of Identifiability

Stage 1 is the latent variable model and Stage 2 is the measurement model.

- Show the parameters of the latent variable model $(\beta, \Gamma, \Phi_x, \Psi)$ can be recovered from $\Phi = cov(\mathbf{F}_i)$.
- Solve $\begin{pmatrix} cov(\mathbf{x}_i) & cov(\mathbf{x}_i, \mathbf{y}_i) \\ cov(\mathbf{y}_i, \mathbf{x}_i) & cov(\mathbf{y}_i) \end{pmatrix} = \mathbf{\Phi} = \begin{pmatrix} \mathbf{\Phi}_{11} & \mathbf{\Phi}_{12} \\ \mathbf{\Phi}_{12}^\top & \mathbf{\Phi}_{22} \end{pmatrix}$ for $(\boldsymbol{\beta}, \boldsymbol{\Gamma}, \mathbf{\Phi}_x, \boldsymbol{\Psi})$?
- Show the parameters of the measurement model (Λ, Φ, Ω) can be recovered from $\Sigma = cov(\mathbf{d}_i)$.
- This means all the parameters can be recovered from Σ .
- Break a big problem into two smaller ones.
- Develop *rules* for checking identifiability at each stage.
- Just look at the path diagram.

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http://www.utstat.toronto.edu/brunner/oldclass/431s23