Exploratory Factor Analysis

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Factor Analysis: The Measurement Model

 $\mathbf{D}_i = \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i$



Example with 2 factors and 8 observed variables

 $\mathbf{D}_i = \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i$



The lambda values are called **factor loadings**.

Terminology

$$D_{i,1} = \lambda_{11}F_{i,1} + \lambda_{12}F_{i,2} + e_{i,1}$$

$$D_{i,2} = \lambda_{21}F_{i,1} + \lambda_{22}F_{i,2} + e_{i,2} \text{ etc.}$$

- The lambda values are called **factor loadings**.
- F₁ and F₂ are sometimes called common factors, because they influence all the observed variables.
- Error terms e₁, ..., e₈ are sometimes called unique factors, because each one influences only a single observed variable.

Factor Analysis can be

- Exploratory: The goal is to describe and summarize the data by explaining a large number of observed variables in terms of a smaller number of latent variables (factors). The factors are the reason the observable variables have the correlations they do.
- **Confirmatory**: Statistical estimation and testing as usual.

Unconstrained (Exploratory) Factor Analysis



- Arrows from all factors to all observed variables.
- Massively non-identifiable.
- Reasonable, been going on for around 70-100 years, and completely DOOMED TO FAILURE as a method of statistical estimation.

Calculate the covariance matrix

$$egin{array}{rcl} \mathbf{D}_i &=& \mathbf{\Lambda}\mathbf{F}_i + \mathbf{e}_i \ cov(\mathbf{F}_i) &=& \mathbf{\Phi} \ cov(\mathbf{e}_i) &=& \mathbf{\Omega} \end{array}$$

 \mathbf{F}_i and \mathbf{e}_i independent (multivariate normal)

$cov(\mathbf{D}_i) = \mathbf{\Sigma} = \mathbf{\Lambda} \mathbf{\Phi} \mathbf{\Lambda}^\top + \mathbf{\Omega}$

A Re-parameterization

$\Sigma = \Lambda \Phi \Lambda^+ + \Omega$

Square root matrix: $\mathbf{\Phi} = \mathbf{S}\mathbf{S} = \mathbf{S}\mathbf{S}^{\top}$, so

$$\begin{split} \mathbf{\Lambda} \mathbf{\Phi} \mathbf{\Lambda}^\top &= \mathbf{\Lambda} \mathbf{S} \mathbf{S}^\top \mathbf{\Lambda}^\top \\ &= (\mathbf{\Lambda} \mathbf{S}) \mathbf{I} (\mathbf{S}^\top \mathbf{\Lambda}^\top) \\ &= (\mathbf{\Lambda} \mathbf{S}) \mathbf{I} (\mathbf{\Lambda} \mathbf{S})^\top \\ &= \mathbf{\Lambda}_2 \mathbf{I} \mathbf{\Lambda}_2^\top \end{split}$$

Parameters are not identifiable

 $\boldsymbol{\Sigma} = \boldsymbol{\Lambda} \boldsymbol{\Phi} \boldsymbol{\Lambda}^{ op} + \boldsymbol{\Omega} = \boldsymbol{\Lambda}_2 \mathbf{I} \boldsymbol{\Lambda}_2^{ op} + \boldsymbol{\Omega}$

- Two distinct (Lambda, Phi, Omega) sets give the same Sigma, and hence the same distribution of the data (under normality).
- Actually, there are infinitely many. Let **Q** be an arbitrary covariance matrix for **F**.

$$\begin{split} \mathbf{\Lambda}_{2}\mathbf{I}\mathbf{\Lambda}_{2}^{\top} &= \mathbf{\Lambda}_{2}\mathbf{Q}^{-\frac{1}{2}}\mathbf{Q}\mathbf{Q}^{-\frac{1}{2}}\mathbf{\Lambda}_{2}^{\top} \\ &= (\mathbf{\Lambda}_{2}\mathbf{Q}^{-\frac{1}{2}})\mathbf{Q}(\mathbf{Q}^{-\frac{1}{2}\top}\mathbf{\Lambda}_{2}^{\top}) \\ &= (\mathbf{\Lambda}_{2}\mathbf{Q}^{-\frac{1}{2}})\mathbf{Q}(\mathbf{\Lambda}_{2}\mathbf{Q}^{-\frac{1}{2}})^{\top} \\ &= \mathbf{\Lambda}_{3}\mathbf{Q}\mathbf{\Lambda}_{3}^{\top} \end{split}$$

Restrict the model

$$\mathbf{\Lambda} \mathbf{\Phi} \mathbf{\Lambda}^{ op} = \mathbf{\Lambda}_2 \mathbf{I} \mathbf{\Lambda}_2^{ op}$$

- Set Phi = the identity, so cov(F) = I
- All the factors are standardized, as well as independent.
- Justify this on the grounds of simplicity.
- Say the factors are "orthogonal" (at right angles, uncorrelated).

Another Source of non-identifiability R is an orthoganal (rotation) matrix

$$\begin{split} \boldsymbol{\Sigma} &= \boldsymbol{\Lambda}\boldsymbol{\Lambda}^\top + \boldsymbol{\Omega} \\ &= \boldsymbol{\Lambda}\mathbf{R}\mathbf{R}^\top\boldsymbol{\Lambda}^\top + \boldsymbol{\Omega} \\ &= (\boldsymbol{\Lambda}\mathbf{R})(\mathbf{R}^\top\boldsymbol{\Lambda}^\top) + \boldsymbol{\Omega} \\ &= (\boldsymbol{\Lambda}\mathbf{R})(\boldsymbol{\Lambda}\mathbf{R})^\top + \boldsymbol{\Omega} \\ &= \boldsymbol{\Lambda}_2\boldsymbol{\Lambda}_2^\top + \boldsymbol{\Omega} \end{split}$$

Infinitely many rotation matrices produce the same Sigma.

A Solution

- Place some restrictions on the factor loadings, so that the only rotation matrix that preserves the restrictions is the identity matrix. For example, $\lambda_{ii} = 0$ for j>i
- There are other sets of restrictions that work.
- Generally, they result in a set of factor loadings that are impossible to interpret. Don't worry about it.
- Estimate the loadings by maximum likelihood. Other methods are possible but used much less than in the past.
- All (orthoganal) rotations result in the same value of the likelihood function (the maximum is not unique).
- Rotate the factors (that is, post-multiply the estimated loadings by a rotation matrix) so as to achieve a simple pattern that is easy to interpret.
- The result is often satisfying, but has no necessary connection to reality.

Consulting advice

- When a non-statistician claims to have done a "factor analysis," ask what kind.
- Usually it was a principal components analysis.
- Principal components are linear combinations of the observed variables. They come from the observed variables by direct calculation.
- In true factor analysis, it's the observed variables that arise from the factors.
- So principal components analysis is kind of like backwards factor analysis, though the spirit is similar.
- Most factor analysis software (SAS, SPSS, etc.) does principal components analysis by default.

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